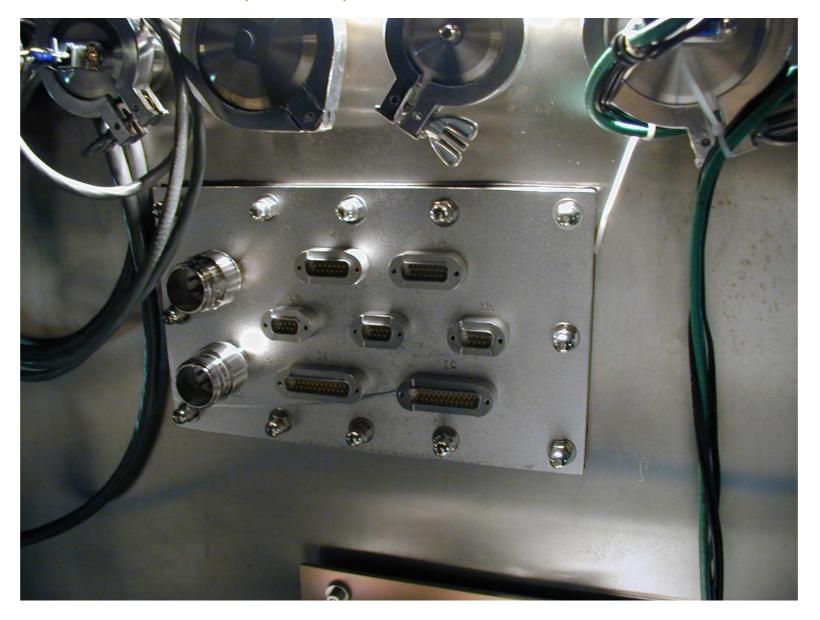
Test deployment of the 4π instrumentation unit

Fred Gray – University of California, Berkeley KamLAND collaboration meeting, Gatlinburg, TN – April 2-4, 2005

...with many thanks to Kengo!

Nose under the (clean) tent



Instrumentation unit

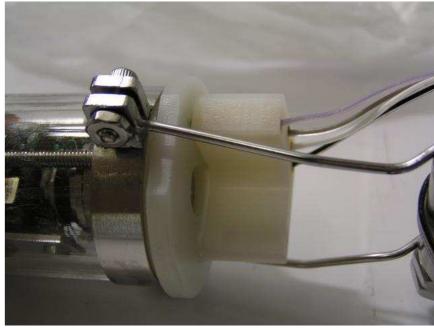


- Pressure sensor
- Thermometer
- ➤ Three-axis accelerometer
- ► Two IR LEDs (830 nm)

Deployed to a depth of 18 m below the bottom of the glovebox in 1 m steps

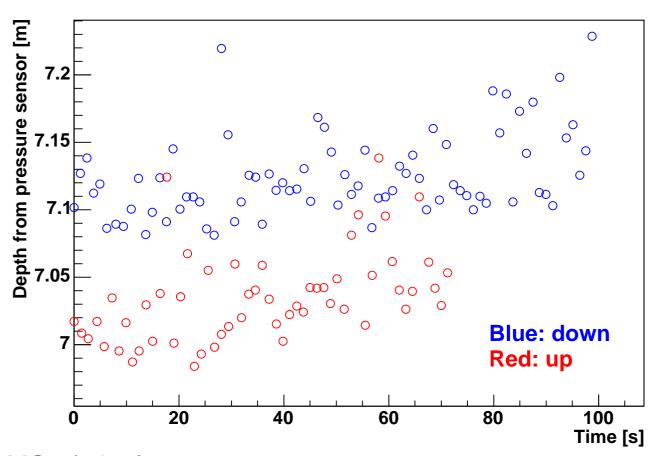
Two early lessons





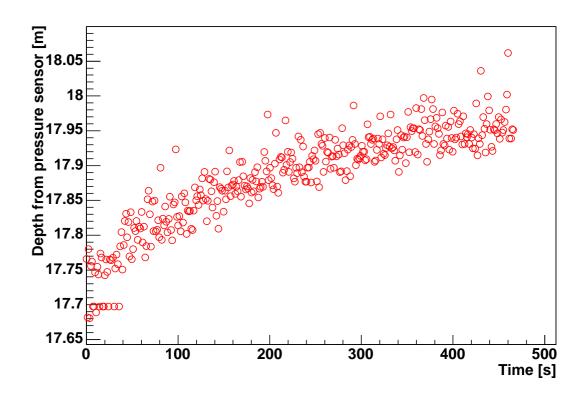
- ▶ Pressure test failure (January 2005)
- Connector thumbscrew mismatch

Pressure sensor resolution



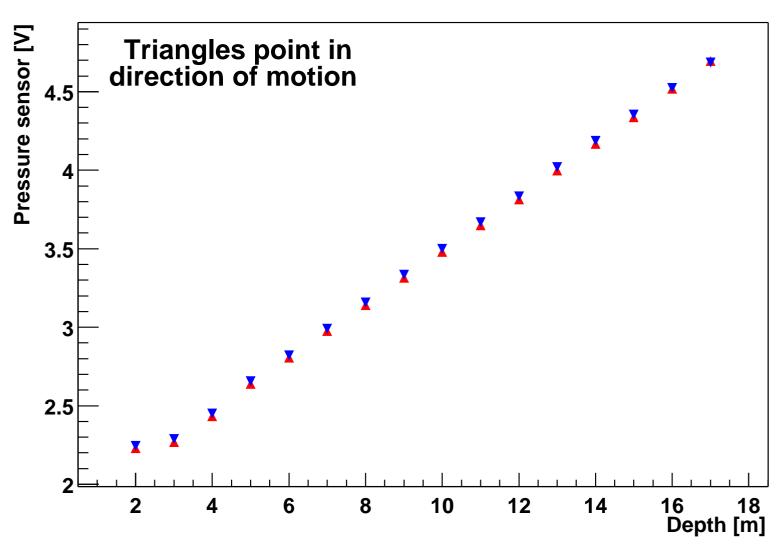
- ▶ RMS of single measurement ≃ 4 cm
- ▶ 1 measurement per second; 0.5 cm in one minute

Pressure fluctuations from glovebox

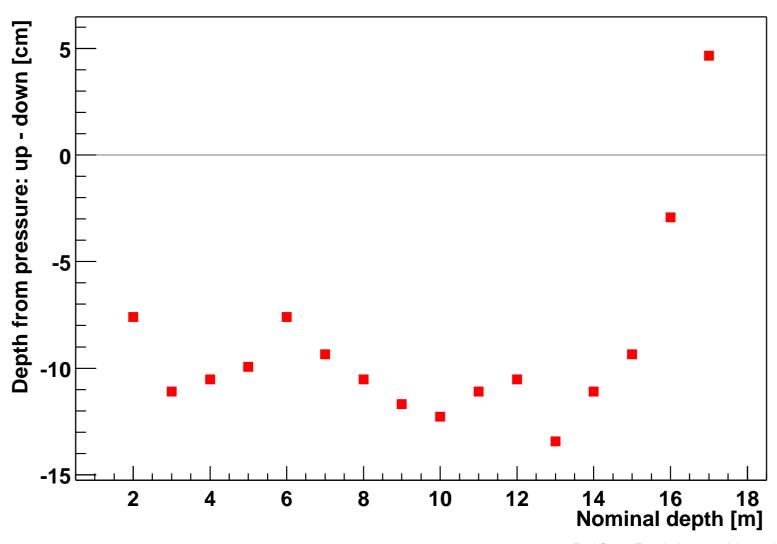


- Instantaneous "spike" followed by slow recovery to atmospheric pressure through glovebox leak.
- Need reference pressure sensor in glovebox.

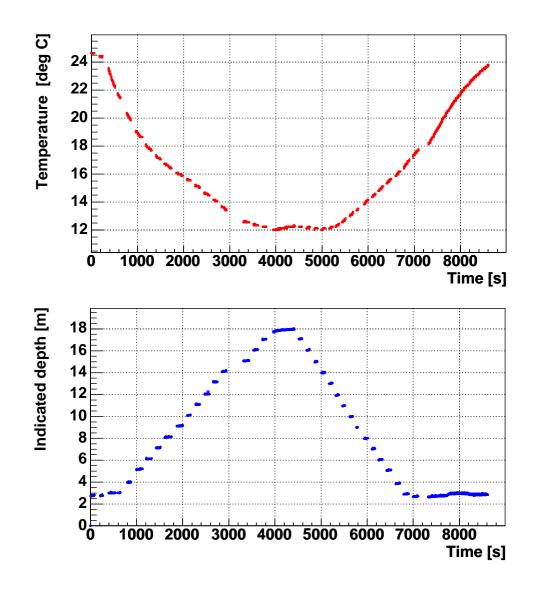
Pressure: down vs. up



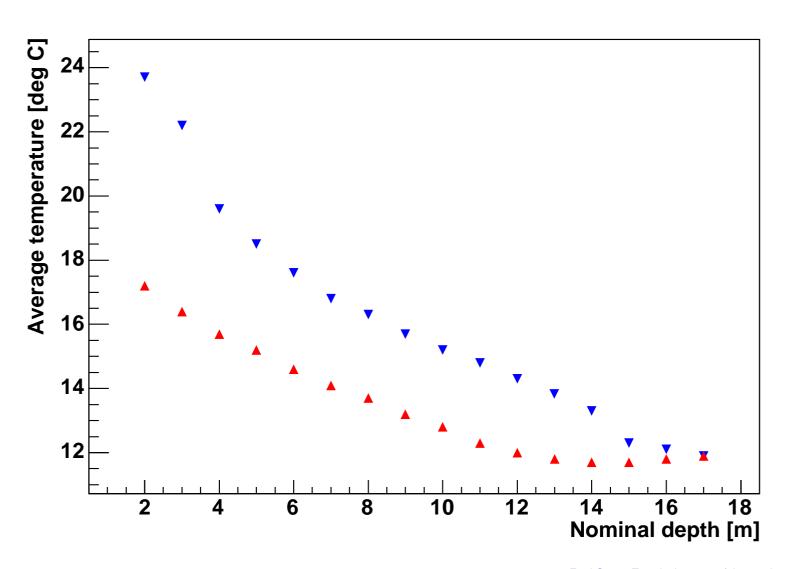
Difference in pressure: down vs. up



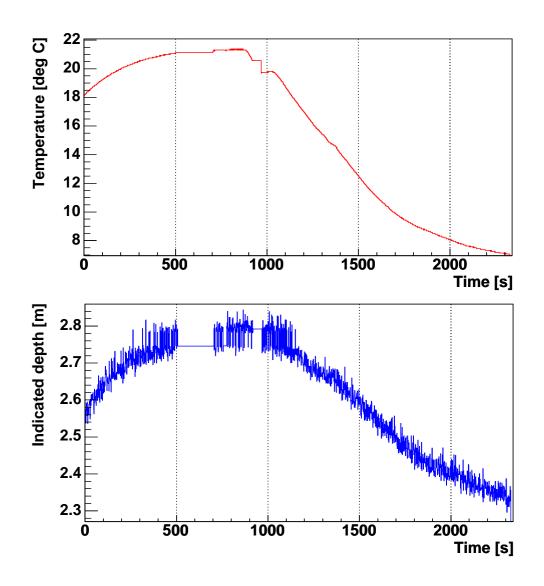
Temperature profile



Mean temperature vs. depth



Pressure vs. temperature in ice H_2O



Conclusion

By preparing for and carrying out this test deployment, we learned a number of lessons:

- ▶ Lucite enclosure made pressure-tight
- Problem with connector thumbscrew fixed
- Need for reference sensor in glovebox established
- Need for temperature correction established
- ...and, we found that the instrumentation unit basically works!

Again, these results would not have been possible without Kengo's help.